

Compact magnetic

Sendix M3653A / M3673A (shaft / hollow shaft)

SSI



The Sendix M36 is a magnetic singleturn encoder in compact design. It is characterized by robustness, reliability and cost-efficiency.

















capacity



resistant





Reverse polarity protection

Surface protection salt spray tested

Reliable and insensitive

- Sturdy bearing construction in Safety-Lock[™] design for resistance against vibration and installation errors.
- · Reduced number of components ensures magnetic insensitivity.
- IP67 protection and wide temperature range -40 °C ... +85 °C.

Application oriented

- Absolute accuracy ±1°.
- Repeat accuracy ±0.2°.
- Short control cycles, clock frequency with SSI up to 2 MHz.
- · Max. resolution 14 bit.

Order code **Shaft version**



If for each parameter of an encoder the underlined preferred option is selected, then the delivery time will be 10 working days for a maximum of 10 pieces. Qts. up to 50 pcs. of these types generally have a delivery time of 15 working days $\frac{1}{2}$



- a Flange
- 1 = clamping flange, IP67, ø 36 mm [1.42"]
- 3 = clamping flange, IP65, ø 36 mm [1.42"]
- 2 = synchro flange, IP67, ø 36 mm [1.42"]
- 4 = synchro flange, IP65, ø 36 mm [1.42"]
- **b** Shaft (ø x L), with flat
- $1 = \emptyset 6 \times 12.5 \text{ mm} [0.24 \times 0.49"]$
- $3 = \emptyset 8 \times 15 \text{ mm} [0.32 \times 0.59"]$
- $5 = \emptyset 10 \times 20 \text{ mm} [0.39 \times 0.79"]$
- $2 = \emptyset 1/4" \times 12.5 \text{ mm} [0.49"]$
- © Interface / supply voltage 2 = SSI / 10 ... 30 V DC

- **d** Type of connection
- 1 = axial cable, 1 m [3.28'] PUR
- A = axial cable, special length PUR *)
- 2 = radial cable, 1 m [3.28'] PUR
- B = radial cable, special length PUR *)
- 3 = axial M12 connector, 8-pin
- 4 = radial M12 connector, 8-pin
- *) Available special lengths (connection types A, B): 2, 3, 5, 8, 10, 15 m [5.56, 9.84, 16.40, 26.25, 32.80, 49.21'] order code expansion .XXXX = length in dm ex.: 8.M3653A.432A.G312.0030 (for cable length 3 m)
- Code
- B = SSI, binary
- G = SSI, gray

- Resolution
- A = 10 bit
- 2 = 12 bit
- 3 = 13 bit
- 4 = 14 bit

Optional on request

- Ex 2/22 (only for connection types 3 and 4)
- surface protection salt spray tested



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Order code Hollow shaft If for each parameter of an encoder the <u>underlined preferred option</u> is selected, then the delivery time will be 10 working days for a maximum of 10 pieces.

Qts. up to 50 pcs. of these types generally have a delivery time of 15 working days.



a Flange

2 = with stator coupling, IP65, ø 46 mm [1.81"]

3 = with spring element, long, IP65

5 = with stator coupling, IP67, ø 46 mm [1.81"]

6 = with spring element, long, IP67

Blind hollow shaft

(insertion death me

(insertion depth max. 18.5 mm [0.73"])

 $1 = \emptyset 6 \text{ mm } [0.24'']$

3 = Ø 8 mm [0.32"]

4 = ø 10 mm [0.39"]

 $2 = \emptyset 1/4''$

Interface / supply voltage

2 = SSI / 10 ... 30 V DC

d Type of connection

1 = axial cable, 1 m [3.28'] PUR

A = axial cable, special length PUR *)

2 = radial cable, 1 m [3.28'] PUR

B = radial cable, special length PUR *)

3 = axial M12 connector, 8-pin

4 = radial M12 connector, 8-pin

*) Available special lengths (connection types A, B): 2, 3, 5, 8, 10, 15 m [5.56, 9.84, 16.40, 26.25, 32.80, 49.21'] order code expansion .XXXX = length in dm ex.: 8.M3673A.242A.G312.0030 (for cable length 3 m)

Code

B = SSI, binary

G = SSI, gray

Resolution

A = 10 bit

2 = 12 bit

3 = 13 bit

4 = 14 bit

Optional on request

- Ex 2/22 (only for connection types 3 and 4)

- surface protection salt spray tested

Mounting accessory for shaf	Mounting accessory for shaft encoders						
Coupling	Bellows coupling ø 19 mm [0.75"] for shaft 8 mm [0.32"]	8.0000.1102.0808					
Mounting accessory for holl	Mounting accessory for hollow shaft encoders Dimensions in mm [inch]						
Torque pin, ø 4 mm for flange with spring element	with fixing thread	8.0010.4700.0000					
(flange type 3 + 6)	8[0,31] 5[0,2] SW7 [0,28] 30[1,18]						
Cables and connectors		Order no.					
Preassembled cables	M12 female connector with coupling nut, 8-pin, A coded, straight open ended 2 m [6.56'] PUR cable	05.00.6051.8211.002M					
Connectors	M12 female connector with coupling nut, 8-pin, A coded, straight (metal)	05.CMB 8181-0					

Further Kübler accessories can be found at: kuebler.com/accessories

Further Kübler cables and connectors can be found at: kuebler.com/connection-technology



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Technical data

Mechanical cha	racteristics	
Maximum speed shaft or blind hollow without shaft seal (I		6000 min ⁻¹ 3000 min ⁻¹ (continuous)
shaft or blind hollow with shaft seal (IP67		4000 min ⁻¹ 2000 min ⁻¹ (continuous)
Starting torque at 20	0°C [68°F]	
	without shaft seal	< 0.007 Nm
1	with shaft seal (IP67	< 0.01 Nm
Shaft load capacity	radial	40 N
,	axial	20 N
Weight		approx. 210 g [7.41 oz]
Protection acc. to E	N 60529	IP65 or IP67
	14 00323	11 00 01 11 07
Working temperatu		-40 °C +85 °C [-40 °F +185 °F]
Working temperature Materials		
Materials	re range shaft / hollow shaft flange housing	-40 °C +85 °C [-40 °F +185 °F] stainless steel aluminum zinc die-cast

Electrical characteristics						
Supply voltage	10 30 V DC					
Current consumption (no load)	max. 40 mA					
Reverse polarity protection of the supply voltage	yes					
Short-circuit proof outputs	yes 1)					

SSI interface	
Output driver	RS485 transceiver type
Permissible load / channel	max. +/- 30 mA
Signal level HIGH LOW with $I_{Load} = 20 \text{ mA}$	typ 3.8 V typ 1.3 V
Resolution	10 14 bit
Absolute accuracy 2)	±1°
Repeat accuracy	±0.2°
Number of revolutions (multiturn)	max. 24 bit
Code	binary or gray
SSI clock rate	50 kHz 2 MHz
Data refresh rate	2 ms
Monoflop time	≤ 15 µs

Note: If the clock cycle starts within the monoflop time a second data transfer begins with the same data. If the clock cycle starts after the monoflop time the cycle begins with the new values. The update rate is dependent on the clock speed, data length and monoflop time.

SET input		
Input		active HIGH
Input type		comparator
Signal level (+V = supply voltage)	HIGH LOW	min. 60 % of +V, max: +V max. 30 % of +V
Input current		< 0.5 mA
Min. pulse duration (SET)		10 ms
Input delay		1 ms
New position data readable after		1 ms
Internal processing time		200 ms

The encoder can be set to zero at any position by means of a HIGH signal on the SET input. Other preset values can be factory-programmed. The SET input has a signal processing time of approx. 1 ms, after which the new position data can be read via SSI. Once the SET function has been triggered, the encoder requires an internal processing time of typ. 200 ms; during this time the supply voltage must not be switched off.

The SET function should be carried out whilst the encoder is at rest.

The number of preset value writing cycles is limited to 10,000.

If this input is not used, it should be connected to 0 V (Encoder ground GND) in order to avoid interferences.

DIR input

Power-ON

Direction input: A HIGH signal switches the direction of rotation from the default cw to ccw. This inverted function can also be factory-programmed.

If this input is not used, it should be connected to 0 V (Encoder ground GND) in order to avoid interferences.

Response time (DIR input) 1 ms

After Power-ON the device requires a time of approx. 150 ms before valid data can be read.

Hot plugging of the encoder should be avoided.

Approvals	
UL compliant in accordance with	File no. E224618
CE compliant in accordance with	
EMC Directive	2014/30/EU
RoHS Directive	2011/65/EU
ATEX Directive	2014/34/EU (for Ex 2/22 variants)
UKCA compliant in accordance with	
EMC Regulations	S.I. 2016/1091
RoHS Regulations	S.I. 2012/3032
UKEX Regulations	S.I. 2016/1107 (for Ex 2/22 variants)

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¹⁾ Short circuit proof to 0 V or to output when supply voltage correctly applied.

²⁾ Over the whole temperature range.



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Terminal assignment

Interface	Type of connection	Features	Cable (isolate unused cores individually before initial start-up)									
2 12AD	OFT DID	Signal:	0 V	+V	C+	C-	D+	D-	SET	DIR	Ŧ	
	1, 2, A, B	SET, DIR	Core color:	WH	BN	GN	YE	GY	PK	BU	RD	shield

Interface	Type of connection	Features	M12 connector, 8-pin										
9	2.4 CET DID	CET DID	Signal:	0 V	+V	C+	C-	D+	D-	SET	DIR	Ŧ	l
2	3, 4	SET, DIR	Pin:	1	2	3	4	5	6	7	8	PH	l

+V: Supply voltage encoder +V DC

0 V: Supply voltage encoder ground GND (0 V)

C+, C-: Clock signal
D+, D-: Data signal
SET: Set input
DIR: Direction input

PH ±: Plug connector housing (shield)

Top view of mating side, male contact base



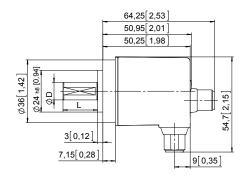
M12 connector, 8-pin

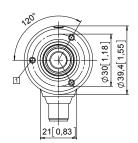
Dimensions shaft version

Dimensions in mm [inch]

Clamping flange, ø 36 [1.42] Flange type 1 and 3

1 3 x M3, 6 [0.24] deep



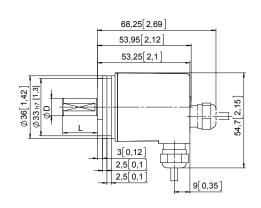


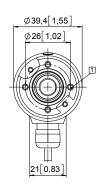
D	Fit	L
6 [0.24]	h7	12.5 [0.49]
8 [0.32]	h7	15 [0.59]
10 [0.39]	f7	20 [0.79]
1/4"	h7	12.5 [0.49]

Synchro flange, ø 36 [1.42] Flange type 2 and 4

1 4 x M3, 6 [0.24] deep

D	Fit	L
6 [0.24]	h7	12.5 [0.49]
8 [0.32]	h7	15 [0.59]
10 [0.39]	f7	20 [0.79]
1/4"	h7	12.5 [0.49]







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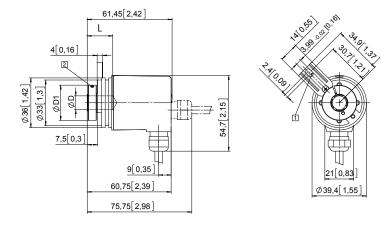
Dimensions hollow shaft version

Dimensions in mm [inch]

Flange with spring element, long Flange type 3 and 6

- Slot spring element, recommendation: torque pin DIN 7, ø 4 [0.16]
- 2 Recommended torque for the clamping ring 0.7 Nm

D	Fit	L	D1					
6 [0.24]	H7	18.5 [0.73]	24 [0.94]					
8 [0.32]	H7	18.5 [0.73]	25.5 [1.00]					
10 [0.39]	H7	18.5 [0.73]	25.5 [1.00]					
1/4" H7 18.5 [0.73] 24 [0.94]								
I = insertion	I = insertion denth max_blind hollow shaft							



Flange with stator coupling, ø 46 [1.81] Flange type 2 and 5 $\,$

1 Recommended torque for the clamping ring 0.7 Nm

D	Fit	L	D1				
6 [0.24]	H7	18.5 [0.73]	24 [0.94]				
8 [0.32]	H7	18.5 [0.73]	25.5 [1.00]				
10 [0.39]	H7	18.5 [0.73]	25.5 [1.00]				
1/4" H7 18.5 [0.73] 24 [0.94]							
L = insertion	L = insertion depth max. blind hollow shaft						

